

## BE1-BPR BREAKER PROTECTION RELAY

The BE1-BPR Breaker Protection Relay provides all the capabilities required for most breaker protection and monitoring functions. It incorporates a simple programming language to allow the user to set up any desired logic between the inputs and outputs.

### ADVANTAGES

- Vertical unit to replace obsolete Breaker Fail relays.
- Horizontal unit for rack-mount installations.
- Powerful "BESTlogic" programming language includes the means to setup and control current signal filters, fault detectors, timers, counters and logic gates.
- Many programmable inputs and outputs for virtually any application: Four AC current and seven isolated contact inputs, five control plus one alarm output, RS-232 and RS-485 communication ports.
- User may program the unit for a specific application or select one of three versatile stored programs with the following functions:
  - Breaker-fail protection
  - Breaker opening resistor protection
  - Breaker "sustained arc" protection
  - Breaker contact duty monitoring

### ADDITIONAL INFORMATION

#### INSTRUCTION MANUAL

Request publication 9-2720-00-990

#### SERVICE MANUAL

Request publication 9-2720-00-620

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|---|
| <b>FEATURES</b><br>Page 2                       |
| <b>APPLICATION</b><br>Page 2                    |
| <b>FUNCTIONAL DESCRIPTION</b><br>Pages 3-6      |
| <b>SPECIFICATIONS</b><br>Page 7                 |
| <b>ORDERING INFORMATION</b><br>Page 7           |
| <b>CONNECTIONS &amp; PANEL CUTOUT</b><br>Page 8 |

## FEATURES

- Easy setup from front panel or communications port.
- Drawout construction with shorting bars on current inputs.
- Monitors breaker contact duty separately for each pole.
- Fault data in COMTRADE format at 12 samples per cycle and up to 200 A. (Ref. IEEE C37.111)
- Communicates with PC equipped with off-the-shelf communications software.
- Built-in diagnostics monitor the health of all major internal functions.
- Time margin log reveals margin on breaker fail timers' settings.
- A high speed relay operating within one-quarter cycle of 60 Hz is provided for breaker-fail output.
- Fault detectors reset within one-quarter cycle of 60 Hz.
- Pickup setting on arc detector can be set below 0.1 A.
- Isolated communications ports.
- IRIG-B time code input to set and synchronize time clock.

## APPLICATIONS

The BE1-BPR provides both breaker protection and breaker monitoring in a single unit that can communicate with a local or remote computer.

### BREAKER PROTECTION

Breaker protection includes breaker fail protection, breaker resistor protection and protection against sustained arcs across one or more open breaker contacts.

Breaker-fail protection is accomplished by initiating a BPR timer from one or more relay trip signal inputs and providing an output to trip upstream breakers if the BPR fault detectors don't drop out before the time expires on the BPR timer.

Breaker opening resistor protection is accomplished by providing an output to block reclosing if BPR calculations determine that additional breaker operations could exceed the maximum resistor power rating.

Open breakers can be protected against sustained arcs by providing an output to close the breaker and allow it to trip again. Such sustained arcs can be initiated by lightning or loss of dielectric strength. Arc current may be limited to line charging current and go undetected by standard fault protection elements. If the arc is allowed to continue for minutes, the breaker will be destroyed due to the internal heat generated. The BPR provides a separate fault detector for detecting low level arcs.

### BREAKER MONITORING

Breaker monitoring generally consists of gathering the data necessary to predict when the breaker contacts should be serviced. This practice eliminates the need to perform routine maintenance on breakers that may be in good condition. Data is acquired each time a 52a/b contact input indicates opening of the breaker.

The BPR not only monitors contact wear but also gathers data on breaker-fail timing margins. This information may be used to help the user achieve fast, secure breaker-fail protection. Data is acquired each time the breaker operates.

The BPR also captures fault data on all four current inputs, along with status on all contact inputs and relay outputs.

The BPR stores the last 12 fault records and overwrites the oldest when full. Recording is triggered according to the trigger conditions setup while programming the relay logic.

Fault data is stored in three forms: An oscillographic record in COMTRADE format, a fault data summary report, and a fault record list.

All data captured can be retrieved by a PC equipped with standard off-the-shelf communications software.

# FUNCTIONAL DESCRIPTION

The diagram below illustrates the general nature of the BPR relay.

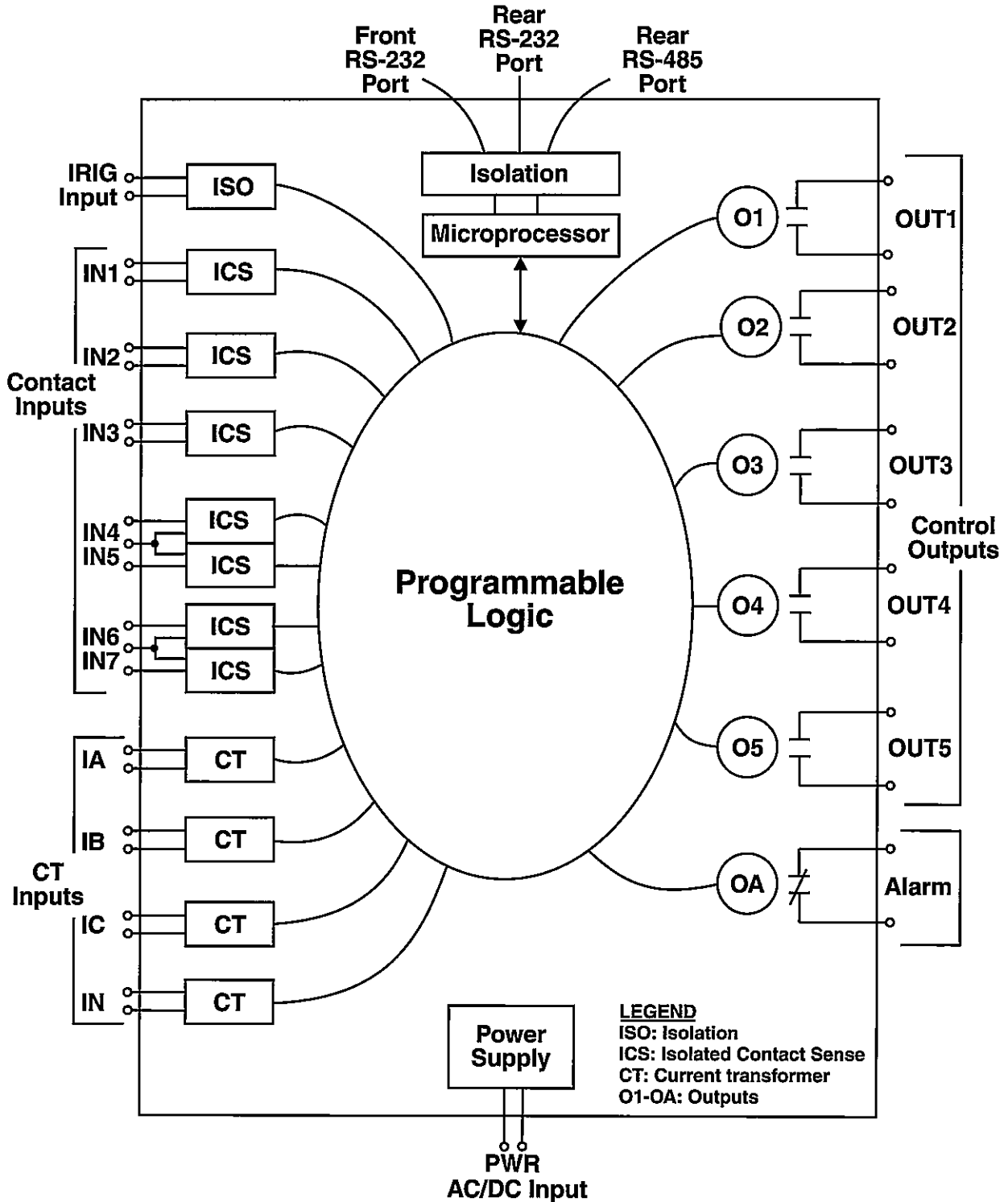
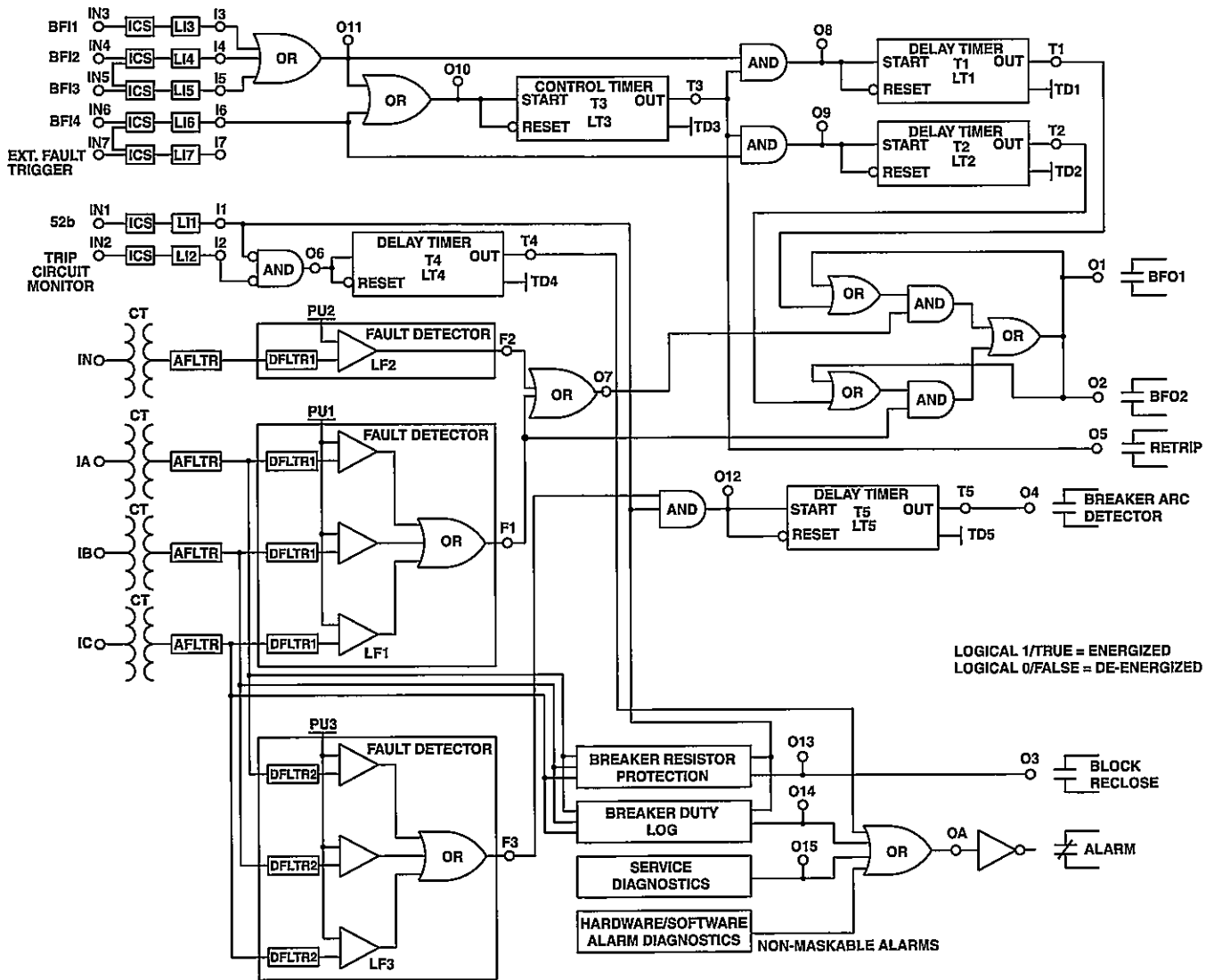


Figure 1 - Functional diagram

## FUNCTIONAL DESCRIPTION (continued)

One example of the programmable logic possible is shown in the diagram below.



**Figure 2 - BFL2E Logic**

BFL2E logic in figure 2 provides the following application features:

1. **Three-Pole Tripping BF Logic** (Output latch-in provided and Control timer limits operational window). Three BFI inputs are available at IN3, IN4, and IN5 to start delay timer T1. If the BFI inputs are not reset by the time T1 times out and either the 3-phase (F1) or neutral (F2) fault detector is still picked up, then outputs BFO1 and BFO2 will close to trip the backup breakers. Control timer (T3) is used to limit the breaker failure window of opportunity.
2. **Single-Pole Tripping BF Logic** (Features: Output latch-in provided and Control timer limits operational window). If single-pole tripping is used, a BFI input is available (IN6) to start delay timer T2. This input is only supervised by the 3-phase fault detector (F1). If the BFI input (IN6) is not reset by the time the timer T2 times out and the 3-phase fault detector (F1) is picked up, outputs BFO1 and BFO2 close, tripping the backup breakers. Control timer T3 is used to limit the breaker failure window of opportunity.

## FUNCTIONAL DESCRIPTION (continued)

Neutral fault detector (F2) is not used to supervise the single-pole BF logic because F2 is still picked up by the phase unbalance after the fault clears. Three-phase BF logic is inhibited during this period because there is no 3-phase BFI input active.

3. **Trip Coil Status Monitor.** Standard logic is provided using IN1 to provide breaker status and IN2 for trip circuit continuity.
4. **Breaker Arc Protection.** Standard logic is provided using fault detector (F3) for the moving average fault detector, IN1 for breaker status and O4 for the arc detector output.
5. **Block Reclose Output.** Standard logic is provided using breaker resistor protection output (O3) to drive the Block Reclose output.
6. **Retrip Output.** A Retrip output is provided to give a backup trip signal to the breaker trip coil. This can either provide a separate path to a single trip coil or be hooked to the backup trip coil if available.
7. **External Fault Trigger.** The enhanced BPR relay provides the ability to save COMTRADE fault records for twelve events in memory at one time. An external fault trigger is provided to permit fault data triggering from an external source.
8. **Alarm Output.** An Alarm output is provided to signal relay failure or diagnostic alarm.

## PROGRAMMING LANGUAGE

The powerful nature of the BESTlogic programming language can be shown by the simple program used to achieve the logic shown in Figure 2. The program is as follows:

```

LN=BFL2E
LF1=PI,1;          LF2=NI,1;          LF3=PI,2
LI1=1,12;          LI2=1,12;          LI3=1,12
LI4=1,12;          LI5=1,12;          LI6=1,12;          LI7=1,12
LT1=D,O8,/O8;      LT2=D,O9,/O9;          LT3=C,O10,/O10
LT4=D,O6,/O6;      LT5=D,O12,/O12;      LT6=0,0,0
LOA=T4+O14+O15
LO1=O2;            LO2=T1O7+F1T2+O1O7
LO3=O13;           LO4=T5;            LO5=T3;            LO6=/I1/I2
LO7=F1+F2;         LO8=T3O11;          LO9=T3I6+T3O9
LO10=I6+O9+O11;   LO11=I3+I4+I5+O8
LO12=F3I1;         LO13=OP_LIMIT;     LO14=DLOG;        LO15=DIAG

```

The first line defines a unique name for the logic set using the LN (Logic Name) command. The next line sets up the fault detectors using the LF (Logic Fault\_detector) command. The third and fourth lines define the input contact debounce logic using the LI (Logic Input) command. The fifth and sixth lines set up the timer/counter functions using the LT (Logic Timer/Counter) command. The final six lines define the boolean output logic using the LO (Logic Output) command.

The BESTlogic commands provide an easy way to define functional elements and use them in logical expressions to achieve the operation desired. Once programmed, different logic sets are activated simply by changing the name of the active logic set using the LOGIC command. Please see the instruction manual for details.

## COMMUNICATIONS COMMAND DESCRIPTIONS

| Command  | Function   |
|--|--|
| ACCESS[= <code>&lt;password&gt;</code> ]   | Read/Change access level in order to change settings               |
| BKRCON [= <code>&lt;Tc(ms)&gt;</code> , <code>&lt;Ti(ms)&gt;</code> , <code>&lt;DMAX(A-S)&gt;</code> ]   | Read/Change breaker contact data                                   |
| BKROPS [= <code>&lt;#operations&gt;</code> , <code>&lt;52a/b contact logic&gt;</code> ]  | Read/Change breaker operations data                                |
| BKRRES [= <code>&lt;lres(A)&gt;</code> , <code>&lt;reset(min)&gt;</code> , <code>&lt;MAXOPS&gt;</code> ]   | Read/Change breaker resistor data                                  |
| CAL [x [= <code>&lt;level&gt;</code> ]]  | Read/Change ADC channel calibration                                |
| COM [x [= <code>&lt;ratedps&gt;</code> ], <code>[Ay]</code> ], <code>[Ey]</code> ], <code>[Hy]</code> ], <code>[Pyy]</code> ], <code>[Xy]</code> ] | Read/Change the serial communications protocol                     |
| CT[P/N [= <code>&lt;ratio&gt;</code> ]]  | Read/Change the Phase or Neutral CT ratio                          |
| DATE [= <code>&lt;dm&gt;</code> / <code>&lt;md&gt;</code> / <code>&lt;yr&gt;</code> ]  | Read/Change the date   |
| DIAG[=0]   | Read/Reset diagnostic log information - alarms                     |
| DLOG[p [= <code>&lt;yy&gt;</code> ]]   | Read/Change the contact duty log                                   |
| FLOG[x [=0]]   | Read fault log or Clear FLOG and FAULT data                        |
| FLT <code>&lt;xxx&gt;</code> <code>&lt;A/B&gt;</code> <code>&lt;.CFG/.DAT&gt;</code>   | Read COMTRADE .DAT/.CFG report for fault <code>&lt;xxx&gt;</code>  |
| FREQ [= <code>&lt;hz&gt;</code> ]  | Read/Change power system frequency                                 |
| HELP/H   | Obtain helpful information   |
| I[p]   | Read phase current in primary units                                |
| ID [= <code>&lt;id&gt;</code> ]  | Read/Change relay ID number for polled communications              |
| LF[x [= <code>&lt;type&gt;</code> ], <code>&lt;dfilt&gt;</code> ]]   | Read/Change Logic for Fault detector operation                     |
| LI[x [= <code>&lt;r&gt;</code> ], <code>&lt;db&gt;</code> ]]   | Read/Change Logic for Contact input                                |
| LINFO [ <code>&lt;name&gt;</code> ]  | Read logics available or <code>&lt;name&gt;</code> logic equations |
| LN [= <code>&lt;name&gt;</code> ]  | Read/Change custom logic name                                      |
| LO[x[= <code>&lt;equation&gt;</code> ]]  | Read/Change Program operation for an output                        |
| LOGIC [= <code>&lt;existing name&gt;</code> ]  | Read/Change the name of the active logic scheme                    |
| LT[x [= <code>&lt;Type&gt;</code> ], <code>&lt;S/C&gt;</code> ], <code>&lt;R&gt;</code> ]]   | Read/Change Logic for Timer/Counter operation                      |
| OUT[x][= <code>&lt;1/0&gt;</code> ]  | Pulse Output ON(1) or OFF(0) for test                              |
| PCLK[= <code>&lt;m/d&gt;</code> ], <code>&lt;12/24&gt;</code> ]  | Read/Program date/time format                                      |
| PDIAG[=LOGIC,TLOG,DLOG,BKR,RESET,CLK,0,0]  | Read/Program diagnostic alarms as ON(1) or OFF(0)                  |
| PDISPLAY[= <code>&lt;default_menu&gt;</code> ], <code>&lt;default_screen&gt;</code> ]  | Read/Program the default display screen                            |
| PTARGET[= <code>&lt;iiiiii&gt;</code> ], <code>&lt;ooooo&gt;</code> ]  | Read/Program the target data format                                |
| PTLOG[x [= <code>&lt;logic&gt;</code> ], <code>[&lt;alarm_type&gt;</code> ], <code>&lt;alarm_time&gt;</code> ]]                                    | Read/Program Timer log logic, alarm type and alarm time            |
| PU[x [= <code>&lt;level&gt;</code> ], <code>&lt;cycles&gt;</code> ]]   | Read/Change an overcurrent pickup level                            |
| PW[x[= <code>&lt;pw&gt;</code> ], <code>&lt;a&gt;</code> ]]  | Used to change the password  |
| QUIT   | Exit programming mode w/o saving changes                           |
| RESET  | Reset latched target data  |
| SAVE   | Exit programming mode and save changes                             |
| SHOWSET  | Read relay setup parameters  |
| SNAME [= <code>&lt;num&gt;</code> ], <code>&lt;name&gt;</code> ]   | Read/Change station name for the COMTRADE report                   |
| STATUS   | Read status of inputs and outputs                                  |
| TARGET   | Read target data   |
| TD[x [= <code>&lt;delay&gt;</code> ], <code>[&lt;inst/max_count&gt;</code> ]]]   | Read/Change timer delay setting                                    |
| TEST [= <code>&lt;reset/test&gt;</code> ]  | Read/Reset diagnostic test results or force test                   |
| TIME [= <code>&lt;hr&gt;</code> : <code>&lt;mn&gt;</code> : <code>&lt;sc&gt;</code> ]  | Read/Change the time   |
| TLOG[x]  | Read Timer log   |
| TRIGGER[= <code>&lt;logic term&gt;</code> /Y]  | Read/Change Trigger logic or trigger a fault record                |
| VER  | Read Model, SN, PN and Program data                                |

## SPECIFICATIONS

### AC CURRENT INPUT

20 amperes, continuous  
400 amperes, one second

### OVERCURRENT DETECTORS

Three are provided and may be set up for 3-phase or neutral

### INSTANTANEOUS OC PICKUP RANGE

0.25 to 9.99 amperes in 0.01 steps

### AVERAGING OC PICKUP RANGE

0.05 to 1.00 amperes in 0.01 steps

### OVERCURRENT PICKUP TIME

21 ms maximum @ 60 Hz

### OVERCURRENT DROP OUT TIME

4.2 ms @ 60 Hz

### OSCILLOGRAPHIC RECORDING RANGE

0 to 200 amperes

### OSCILLOGRAPHIC RECORDING

12 samples per cycle in COMTRADE format

### TIMERS

Six microprocessor controlled timers adjustable from 1 to 999 ms in 1 ms steps or 1 to 65 sec in 0.1 sec steps

### REAL TIME CLOCK

Resolution: 1 ms  
Stability: 30ppm typical

### INPUT CONTACT SENSING RANGE

Same as DC power supply input  
Programmable recognition time, 1-99 ms

### OUTPUT RELAY SPEED

One-quarter cycle maximum on Output #1  
One-half cycle maximum on Outputs #2-5

### DISPLAY

2 line x 16 character backlit LCD display

### OUTPUT CONTACT RATINGS

Make 30 A and carry for 0.2 sec  
Carry 7 A continuous  
Break 0.3 A, L/R=0.04, @ 250Vdc

### TARGETS

Five diagnostic LEDs are provided plus target display of all I/O contacts

### COMMUNICATIONS

Includes front and rear RS-232 ports and an RS-485 port on rear.  
Only one port may be active at a time.  
Oscillographic records conform to IEEE C37.111 - Standard Common Format for Transient Data Exchange (COMTRADE) for Power Systems.  
Protocol: String of ASCII characters

### ISOLATION

2500 Vac on current inputs  
1500 Vac on control inputs and outputs

### SURGE WITHSTAND

Qualified to:  
ANSI/IEEE C37.90.1 - SWC and fast transient  
IEC 255-2 - IEC Impulse

### RADIO FREQUENCY INTERFERENCE

Type tested using a five watt tranceiver from 144 to 440 MHz

### OPERATING TEMPERATURE

-40°C to +70°C (-40°F to +158°F)

### SEISMIC

2g in range of 10 to 500 Hz

### CASE SIZE (Vertical unit)

M1 case size  
6.61"W x 16.2"H x 9.45"D behind panel

### CASE SIZE (Horizontal unit)

Nineteen inch rack mount  
19"W x 3.48"H x 9.4"D behind panel  
or 8.4"D with movable flanges

### POWER SUPPLIES

40 to 150 Vdc (48/125 Vac/dc)  
90 to 300 Vdc (125/250 Vac/dc)

## ORDERING INFORMATION

| PART NUMBER |             | POWER SUPPLY   | CONFIGURATION  |
|-------------|-------------|----------------|----------------|
| VERTICAL    | HORIZONTAL  |                |                |
| BE1-BPR-309 | BE1-BPR-300 | 48/125 Vac/dc  | Basic model    |
| BE1-BPR-311 | BE1-BPR-302 | 48/125 Vac/dc  | Enhanced model |
| BE1-BPR-310 | BE1-BPR-301 | 125/250 Vac/dc | Basic model    |
| BE1-BPR-312 | BE1-BPR-303 | 125/250 Vac/dc | Enhanced model |

The following capabilities are only in the enhanced models:

- Accumulated contact duty
- Fault record list
- Fault summary report
- Oscillographic data

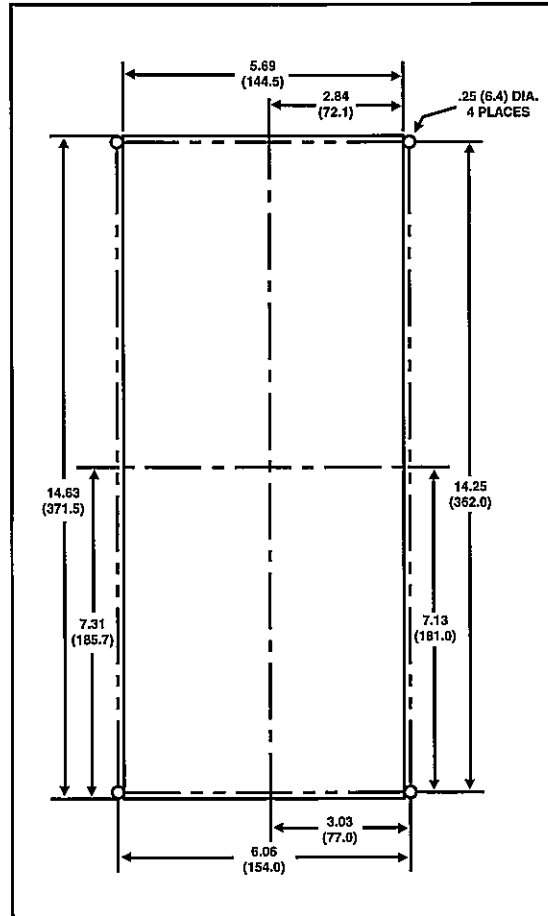


Figure 4 - Panel Cutout Dimensions for Vertical Unit

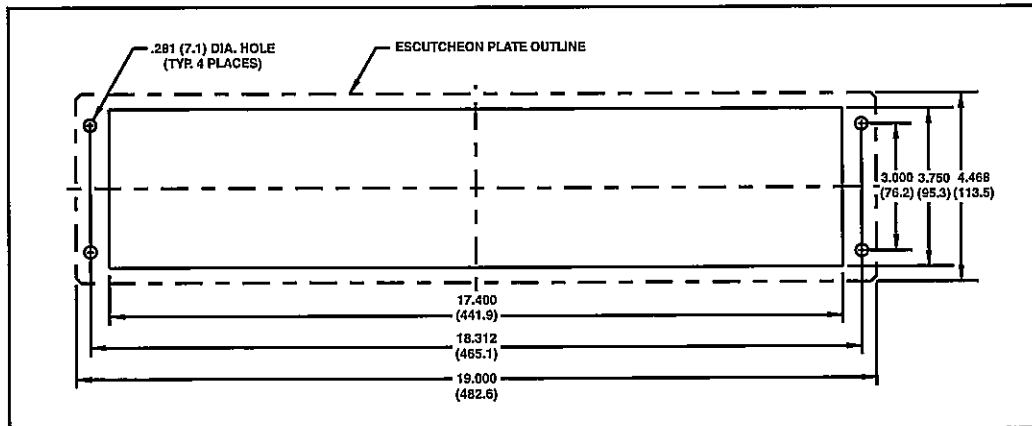


Figure 5 - Panel Cutout Dimensions for Horizontal Unit

**B** Basler Electric